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WHAT IS CLAIMED IS:

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1. An electric power steering apparatus for applying an assisting steering force to a steering mechanism of a vehicle by driving an electric motor according to a steering operation performed by a steering unit for steering the vehicle, comprising:

an electric current command value calculation unit
which calculates an electric current command value by
correcting a target value of an electric current to be

a drive control unit which controls the drive of the
electric motor so that an electric current of the electric current command value flows in the electric motor; and

a convergence control unit which determines a damping compensation value, which is a correction value of the target value to be corrected by the electric current command value calculation unit, so that a quantity of steering operation performed by the steering unit is converged to a neutral point, the convergence control unit including:

a compensation electric current setting unit
which determines a basic damping compensation electric
current value corresponding to the correction value of the
target value based on a steering speed which is a changing

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speed of the quantity of the steering operation and a vehicle speed, and

a compensation electric current adjusting unit
which adjusts the basic damping compensation electric

5 current value based on the steering torque given to the
steering unit and the quantity of the steering operation,
thereby calculating the damping compensation value.

claim 1, wherein the compensation electric current

adjusting unit adjusts the basic damping compensation

electric current value so that the damping compensation

value is increased when the quantity of steering operation

increases more than the neutral point and then decreases

in a predetermined period of time and the steering torque is not higher than a predetermined value.

20 adjusting unit including:

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a gain deciding unit which decides a gain with respect to the basic damping compensation electric current value based on the quantity of operation and the steering torque, and

a multiplication unit which multiplies the basic damping compensation electric current value by the gain, thereby calculating the damping compensation value, and

wherein the gain deciding unit increases the gain

5 when the quantity of operation increases more than the

neutral point and decreases in a predetermined period of

time and the steering torque is not higher than a

predetermined value.

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